A LABORATORY COURSE IN ELECTRICAL MACHINES

CHAPTER 1 General Instructions

1.1 Safety of Personnel

1.2 Instructions for Practical Work

1.3 Machine Specifications

1.4 Selection of Instruments

1.5 Report Writing

CHAPTER 2 Measuring Instruments

2.1 General 2.2 Controlling Force 2.3 Damping Force 2.4 Ammeters and Volmeters 2.4.1 Permanent Magnet Moving-Coil Type 2.4.2 Rectifier Type 2.4.3 Moving-Iron Types 2.4.4 Dynamometer Type 2.5 Wattmeters 2.5.1 Single-Phase Wattmeter 2.5.2 Low Power Factor Wattmeter 2.6 Power Measurement in Three-Phase Circuits 2.6.1 Two-Wattmeter Method 2.6.2 Three-Phase Wattmeter 2.7 Frequency Meters 2.8 Power Factor Meters 2.9 Potential Transformers 2.10 Current Transformers

2.11 Cathode-ray Oscilloscope 2.12 Digital Instruments

CHAPTER 3 Auxiliary Laboratory Equipment

3.1 Rheostats and Resistors

3.2 Loading of Generators

3.2.1 D.C. Generators

3.2.2 A.C. Generators

3.3 Loading of Motors

3.4 Variable Auto-Transformers

3.5 Induction Regulators

3.5.1 Single Phase Induction Regulator

3.5.2 Three Phase Induction Regulator

3.6 Speed Measurement

3.6.1 Electrical Tachometers

3.6.2 Strobscope

3.6.3 Mechanical Tachometers

CHAPTER 4 Machines

4.1 Generator Principle

4.2 Construction

4.3 Motor Principle

- 4.4 D.C. Motor Starters
 - 4.4.1 Shunt and Compound Motor Starters
 - 4.4.2 Seriers Motor Starters
- 4.5 Controllers
- 4.6 Name Plate Data and Terminal Markings

CHAPTER 5 Experiments on D.C. Machines

- 5.1 Measurement of Resistances of Field and Armature Circuits
- 5.2 Operation of D.C. Shunt, Series and Compound Motors-Running and Reversing
- 5.3 Speed Control of D.C. Motors
- 5.4 No-Load Tests on Separately Excited and Shunt-Excited D.C. Generators
- 5.5 Load Tests on Separately Excited and Shunt Excited D.C. Generators
- 5.6 Load Test on Series Generator
- 5.7 Load Test on Compound Generator
- 5.8 Parallel Operation of Shunt and Compound Generators
- 5.9 Load Test on D.C. Shunt Motor and Determination of Performance Characteristics
- 5.10 Load Test on D.C. Series Motor and Determination of Performance Characteristics
- 5.11 Efficiency of D.C. Shunt Motor by Loss-Summation (Swinburne's Method)
- 5.12 Efficiency of D.C. Shunt Machines by Hopkinson's Regenerative Test
- 5.13 Efficiency of D.C. Series Machine by Field's Method

5.14 Rotational Losses of a D.C. Motor and Separation of Iron and Mechanical Losses by Reterdation Test

5.15 Iron and Mechanical Losses of a D.C. Shunt Machine

CHAPTER 6 Experiments on Transformers

6.1 Equivalent Circuit and Voltage Regulation of a Single-Phase Transformer by Open-Circuit and Short Circuit Tests

6.2 Efficiency of a Transformer by Summpner'sBack-to Back Test

6.3 Separation of Hysteresis and Eddy Current Losses of a Transformer

6.4 Parallel Operation of Transformers

6.5 Transformation of Power From a Three-Phase System to Two-Phase System Using Scot Connected Transformers

CHAPTER 7 Experiments on Induction Machines

7.1 Load Test on a Three Phase Induction Motor: Determination of Performance Characteristics

7.2 Circle Diagram of Three Phase Induction Motor from No Load and Blocked Rotor Tests

7.3 Equivalent Circuit of a Single Phase Induction Motor from No-Load and Blocked Rotor Tests

CHAPTER 8 Experiments on Synchronous Machines

8.1 Voltage regulation of an Alternator by (i) Synchronous Impedance Method (ii) Potier Triangle Method (iii) Saturated Synchronous Reactance Method (iv) A.S.A. Method
8.2 Determination of Losses and Efficiency of an Alternator
8.3 Parallel Operation of Alternators
9.4 V. Curruse of a Sur Alternator

8.4 V-Curves of a Synchronous Motor

CHAPTER 9 Experiments on Special Machines

9.1 Load-Voltage Characteristics of a Cross-Field Generator

9.2 Performance Characteristics of a Schrage Motor

CHAPTER 10 Advanced Experiments

10.1 Calibration of a. d. c. Shunt Machine

10.2 Exact Equivalent Circuit of a Transformer

10.3 Effect of Connections in Three Phase Transformers on the Wave Shape of Magnetizing Current

10.4 Equivalent Circuit and Regulation of a Three Winding Transformer

10.5 Determination of Equivalent Circuit Parameters, Sequence Impedances, Stray Load Losses, Torque-Speed Curve and Temperature Rise of an Induction Motor

10.6 Determination of Reactances and Time Constants of a Salient Pole Synchronous Machine